

Exam in Signal analysis and representation, 7.5 credits.

Course code: dt8010

Date: 2011-01-05

Allowed items on the exam:

Tables of Signal processing formulas.

Tables of Mathematical formulas.

Calculator.

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Maximum points: 8.

In order to pass the examination with a grade 3 a minimum of 3.3 points is required.

To get a grade 4 a minimum of 4.9 points is required, and to get a grade 5 a minimum of 6.5 points is required.

Give your answer in a readable way and motivate your assumptions.

Good Luck!

1. (2p)

A LTI system is represented by the difference equation:

$$y(n) - \frac{9}{4}y(n-1) + \frac{1}{2}y(n-2) = \frac{3}{4}x(n) - \frac{5}{8}x(n-1).$$

- a) Sketch the pole-zero pattern of the system $H(z)$. (0.8 p)
 b) Specify the ROC of $H(z)$ and determine $h(n)$ for the following conditions:
 i) The system is stable. (0.6p)
 ii) The system is causal. (0.6p)

2. (2p)

A causal FIR-system is described by its impulse response:

$$h(n) = \frac{1}{3}\delta(n) + \frac{1}{3}\delta(n-1) + \frac{1}{3}\delta(n-2).$$

- a) Compute the frequency response function $H(\omega)$, and sketch the magnitude- and phase-function for $0 \leq \omega \leq 2\pi$.

Present $H(\omega)$ as $H(\omega) = H_{real}(\omega)e^{-j\omega(M-1)/2}$ where $H_{real}(\omega)$ is a real function and M is the length of $h(n)$. (1p)

- b) Determine the steady state response $y(n)$ of the system to the input signal:

$$x(n) = 2 \sin\left(\frac{\pi}{3}(n-1)\right) + 0.5 \cos\left(\frac{2\pi}{3}n\right). \quad (1p)$$

3. (2p)

Consider the causal system

$$H(z) = \frac{1}{1 - z^{-1} + \frac{1}{2}z^{-2}}$$

Determine:

- a) The impulse response $h(n)$. (1p)
 b) The step response when the system is initially relaxed. (1p)

4. (2p)

- a) Compute the 8-point DFT of the causal system:

$$h(n) = \delta(n-3)$$

Present $H(k)$ as: $e^{-jkM} H_{real}(k)$. (0.6p)

- b) Sketch the magnitude- and the phase-function of the system. (0.6p)
 c) Compute the response to the input

$$x(n) = \left[0.8 \cos\left(\frac{3\pi}{4}n\right) + 1.2 \right] u(n). \quad (0.8p)$$

TABLE 3.3 Some Common z -Transform Pairs

	Signal, $x(n)$	z -Transform, $X(z)$	ROC
1	$\delta(n)$	1	All z
2	$u(n)$	$\frac{1}{1 - z^{-1}}$	$ z > 1$
3	$a^n u(n)$	$\frac{1}{1 - az^{-1}}$	$ z > a $
4	$na^n u(n)$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z > a $
5	$-a^n u(-n - 1)$	$\frac{1}{1 - az^{-1}}$	$ z < a $
6	$-na^n u(-n - 1)$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z < a $
7	$(\cos \omega_0 n)u(n)$	$\frac{1 - z^{-1} \cos \omega_0}{1 - 2z^{-1} \cos \omega_0 + z^{-2}}$	$ z > 1$
8	$(\sin \omega_0 n)u(n)$	$\frac{z^{-1} \sin \omega_0}{1 - 2z^{-1} \cos \omega_0 + z^{-2}}$	$ z > 1$
9	$(a^n \cos \omega_0 n)u(n)$	$\frac{1 - az^{-1} \cos \omega_0}{1 - 2az^{-1} \cos \omega_0 + a^2 z^{-2}}$	$ z > a $
10	$(a^n \sin \omega_0 n)u(n)$	$\frac{az^{-1} \sin \omega_0}{1 - 2az^{-1} \cos \omega_0 + a^2 z^{-2}}$	$ z > a $