

Cooperating Intelligent Systems

Constraint satisfaction

Chapter 5, AIMA

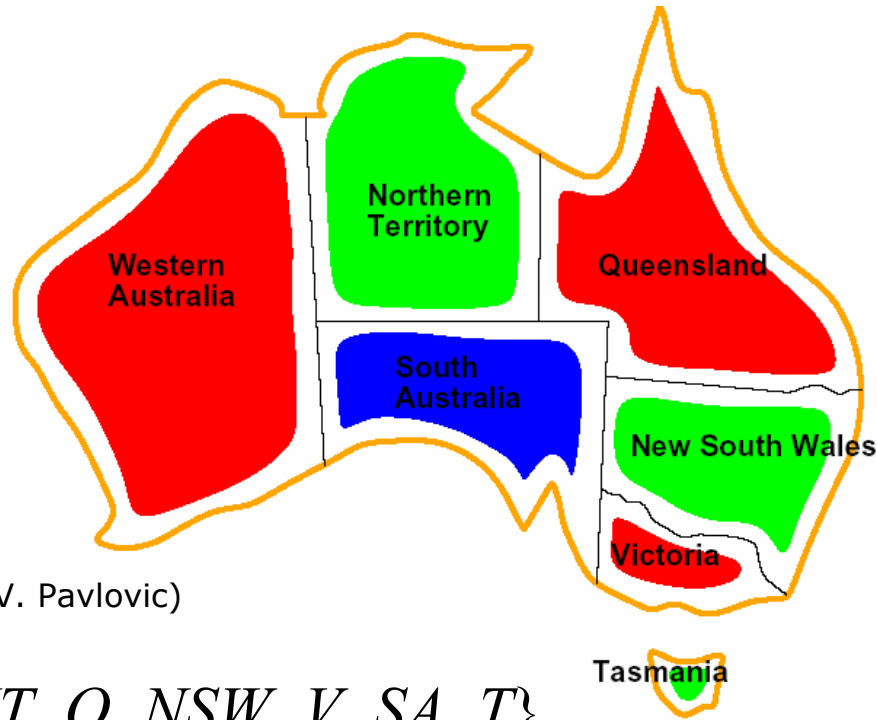
Constraint Satisfaction Problem (CSP)

- A set $\mathbf{X} = \{X_1, X_2, \dots, X_n\}$ of variables
- Each variable X_i has a nonempty domain $\mathbf{D}_i = \{v_1, v_2, \dots, v_{k(i)}\}$ of possible values
- A set $\mathbf{C} = \{C_1, C_2, \dots, C_m\}$ of constraints

- A solution is a complete assignment of values for the variables, which satisfies all the constraints.

- Examples: Map coloring, scheduling, logistics (transportation), N-queens, crossword puzzles,...

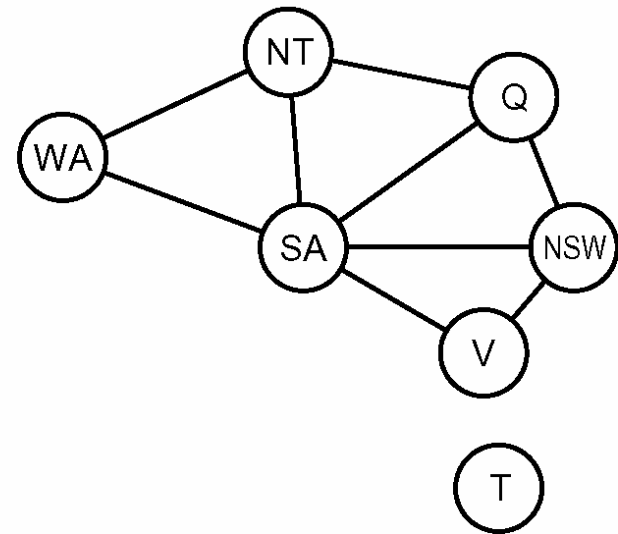
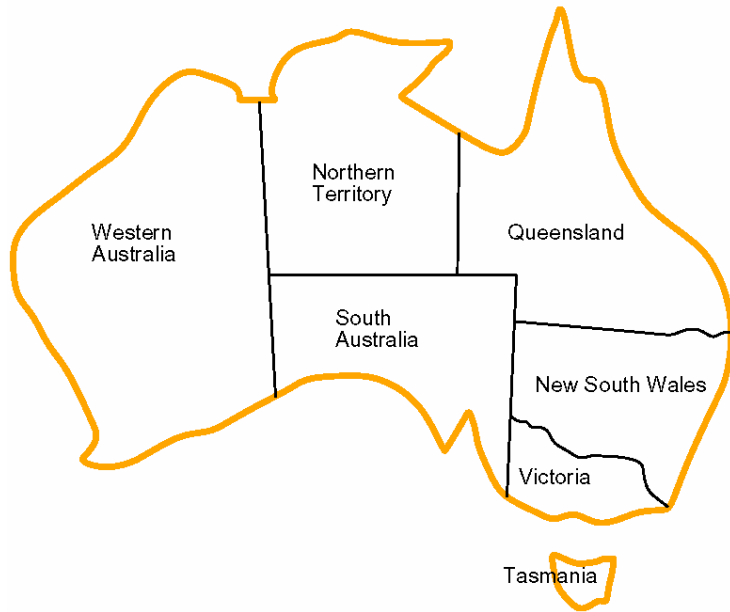
Map coloring



(Image borrowed from V. Pavlovic)

- $\mathbf{X} = \{WA, NT, Q, NSW, V, SA, T\}$
- $\mathbf{D} = \{R, G, B\}$ (for all variables)
- $\mathbf{C} = \{WA \neq NT, WA \neq SA, NT \neq SA, NT \neq Q, SA \neq Q, SA \neq NSW, SA \neq V, Q \neq NSW, NSW \neq V\}$
(Neighboring regions must have different colors)
- Goal: All regions must have a color

Map coloring



- CSP can be visualized with constraint graph
 - Nodes = variables
 - Arcs = constraints

Types of constraints

- Unary: $X_i \neq v_j$
- Binary: $X_i \neq X_j$
- Higher order

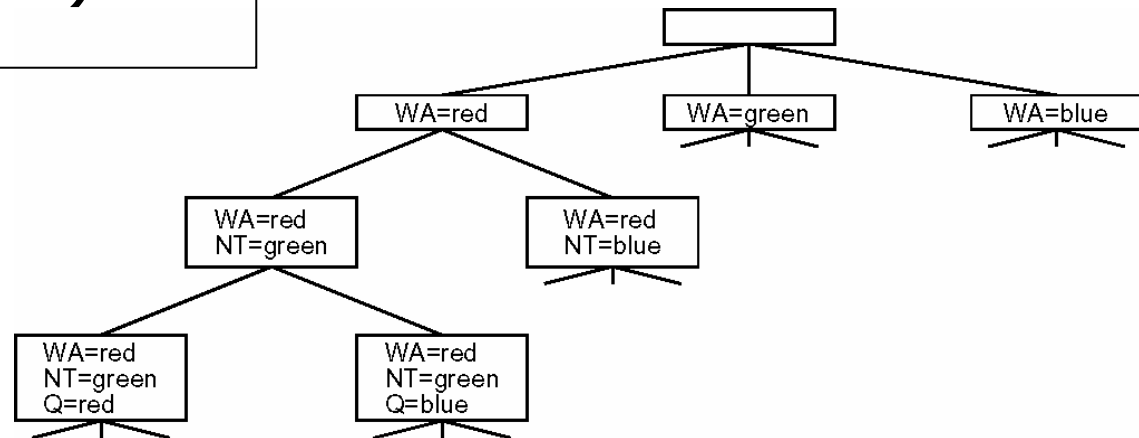
- Preferences

CSP cast as a search problem

- Initial state
- Successor function
- Goal test
- Path cost (not relevant)

- Depth-first search (depth limit = n)

⇒ Backtracking search

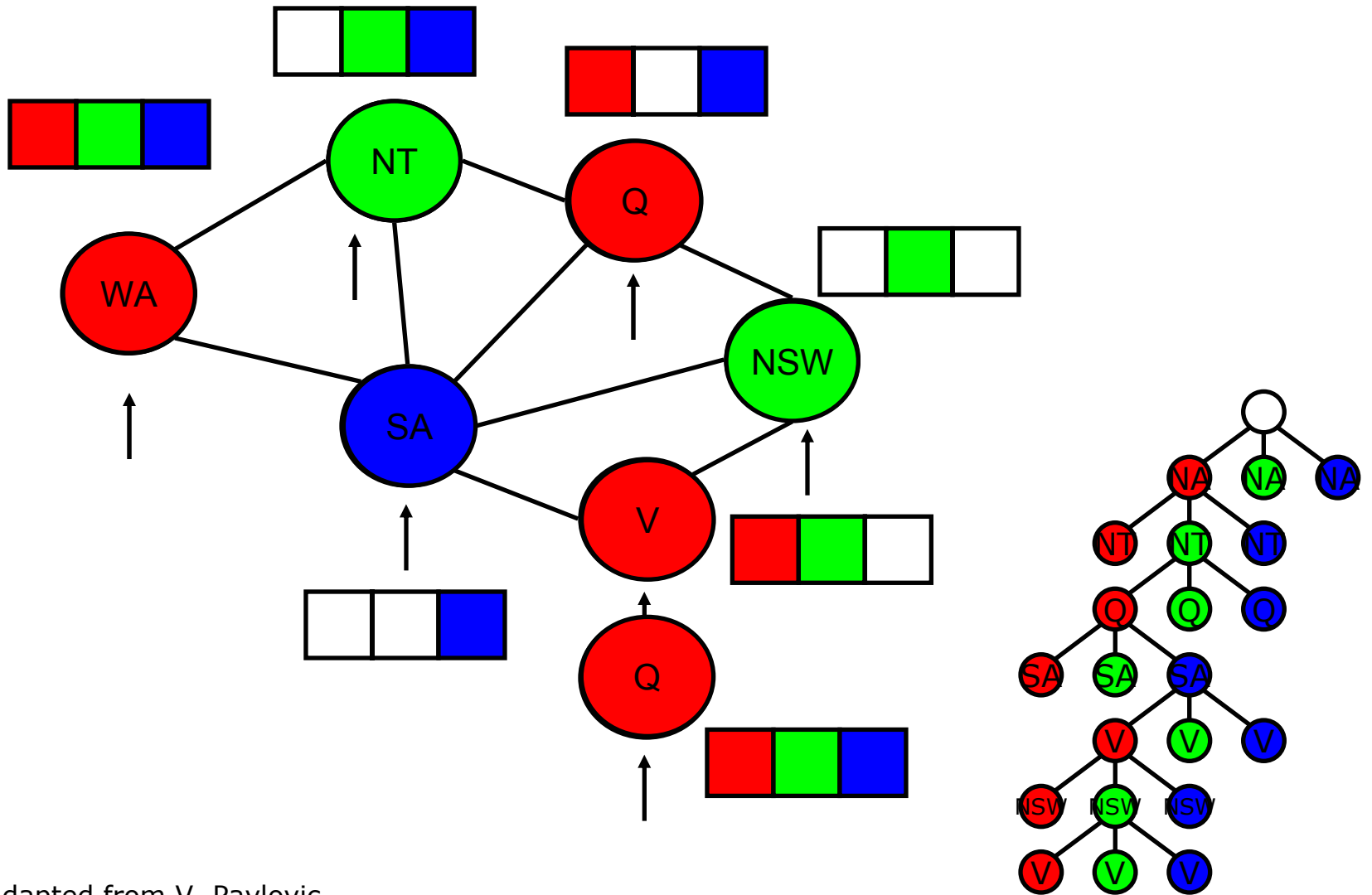


Very inefficient

Improve "vanilla" Backtracking

1. Smart choice of next variable
 - Min. remaining values (+ degree heuristic)
 - Least constraining value
2. Check consequences of choice
 - Forward checking
 - Arc consistency
3. Intelligent backtracking
 - Backjumping

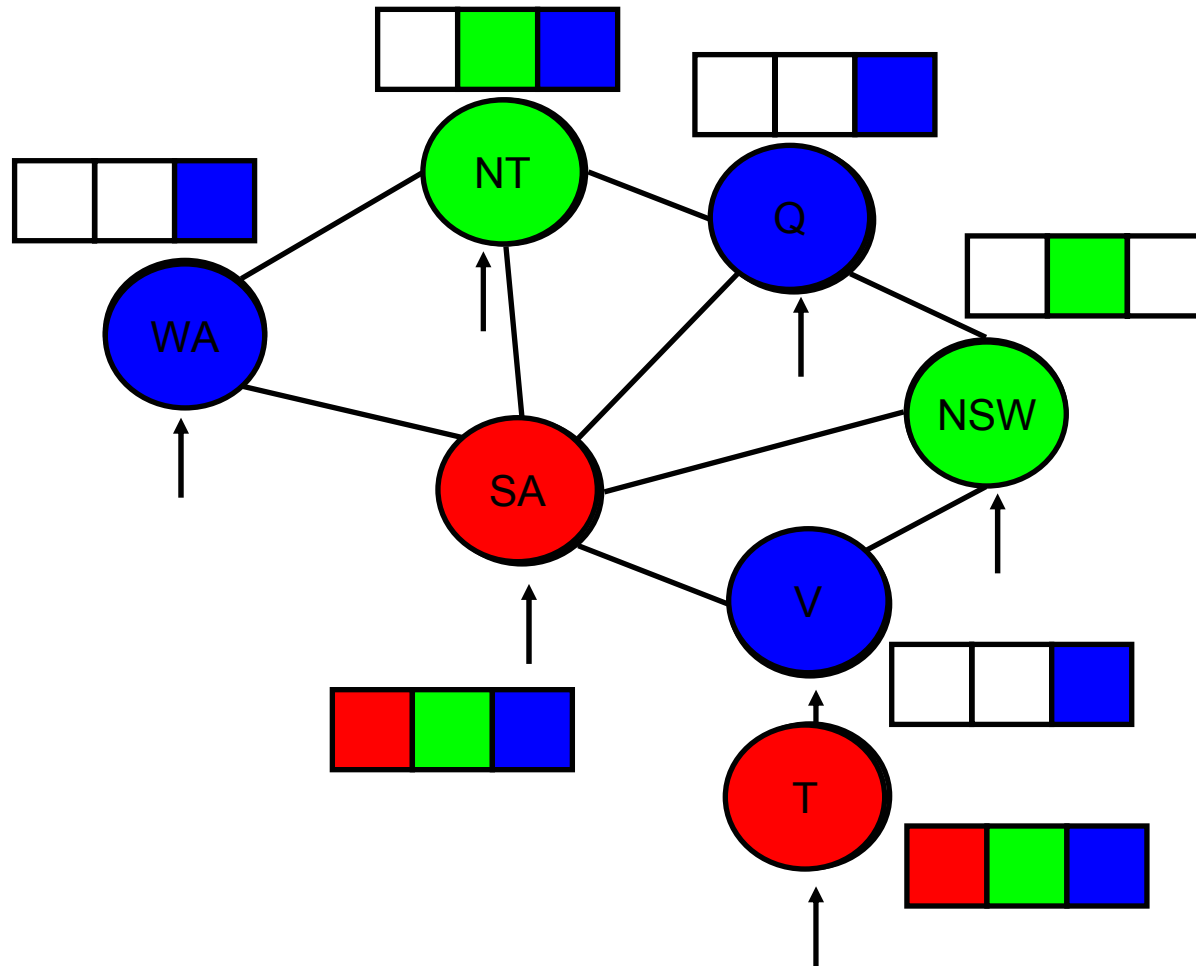
"Vanilla" backtracking



Animation adapted from V. Pavlovic

Minimum remaining values

Choose next the variable that is most constrained based on current assignment (& choose the one with the highest degree first in ties)



Animation adapted from V. Pavlovic

Least constraining value

Select the value that least constrains the other variables
(rules out fewest other variables)

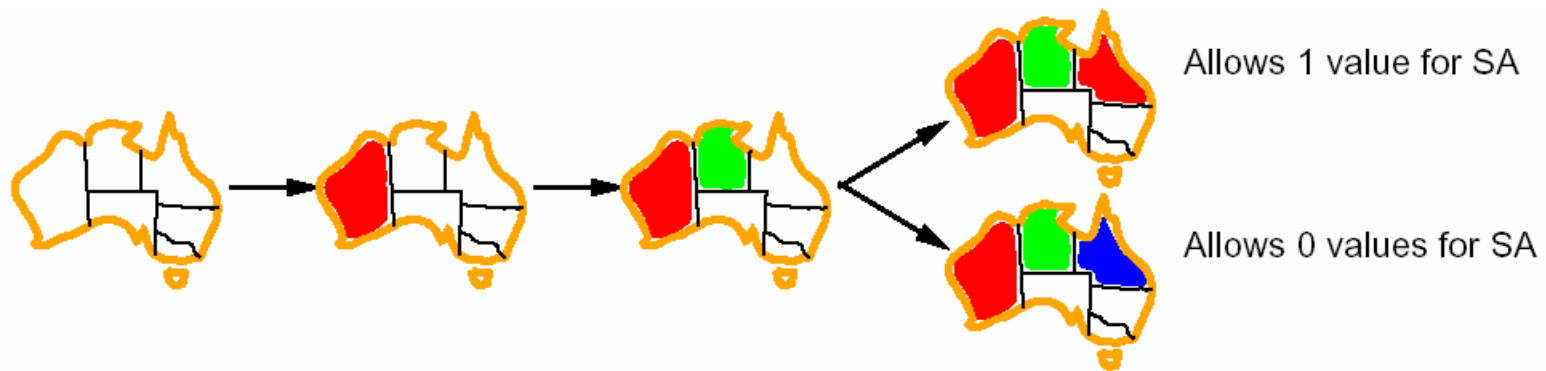
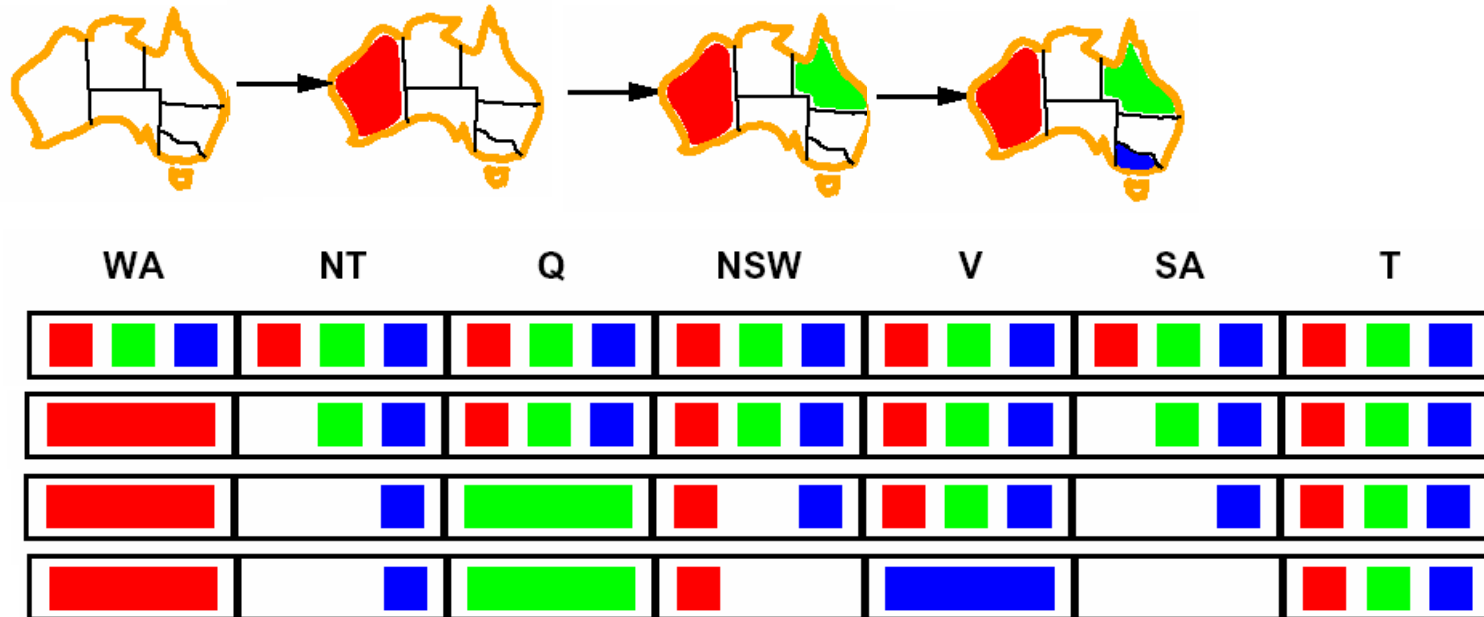


Image borrowed from V. Pavlovic

Forward checking

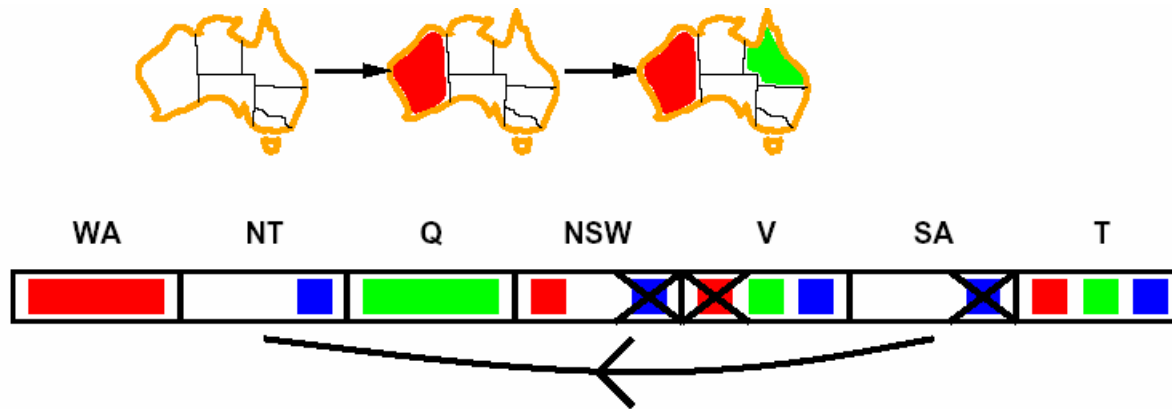
Delete values that are inconsistent with the last selection



Stop search early, if necessary

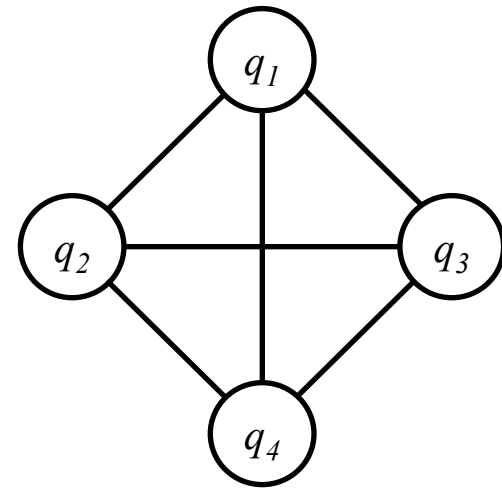
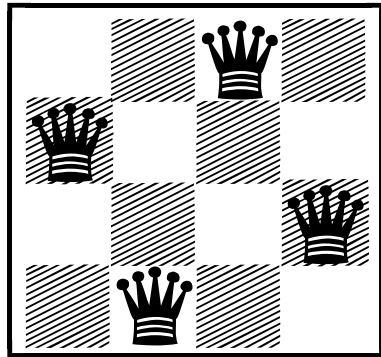
Arc consistency

- The arc $X_i \rightarrow X_j$ is consistent if for every value of X_j there exists some valid value of X_i .



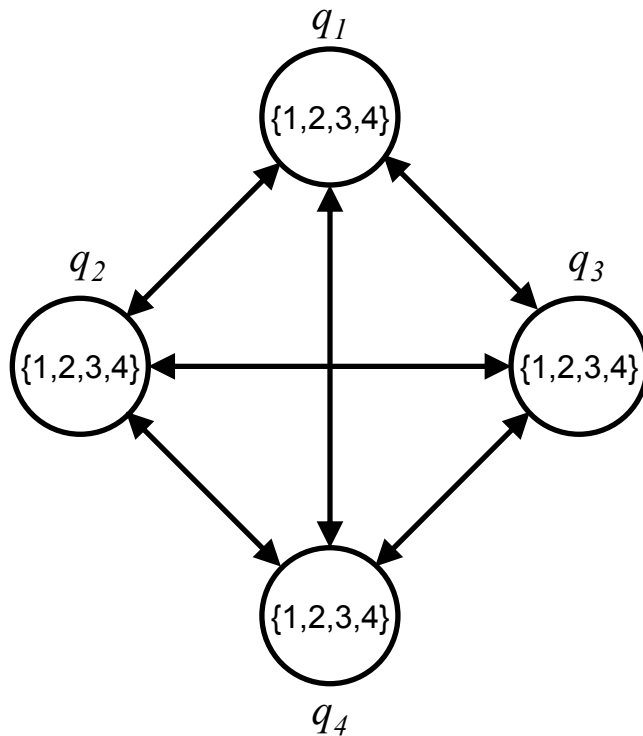
- Detects failures sooner than forward checking.
- Use as preprocessor or as check after each move (MAC)

4-queens



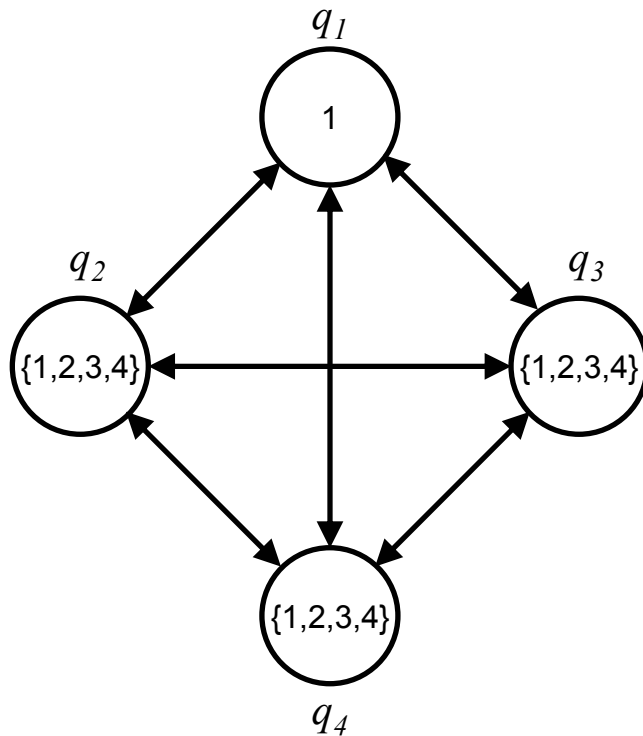
- $\mathbf{X} = \{q_1, q_2, q_3, q_4\}$ ($q_i =$ queen in column i)
- $\mathbf{D} = \{1,2,3,4\}$ (row for queen)
- \mathbf{C} : No queen may attack another queen
- Goal: Place all queens on the board

Arc consistency: 4-queens

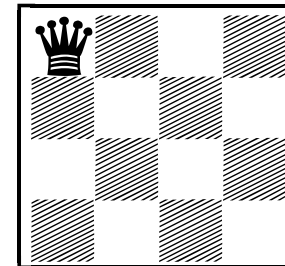


- q_i = queen placed in column i
- $\{1,2,3,4\}$ = The allowed values (row number) for the queen.

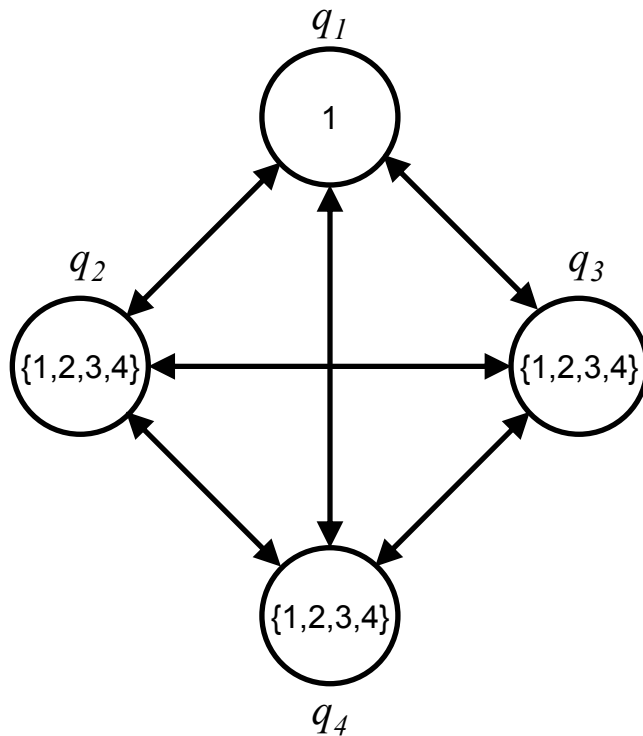
Arc consistency: 4-queens



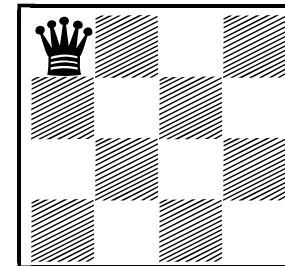
- q_i = queen placed in column i
- $\{1,2,3,4\}$ = The allowed values (row number) for the queen.
- First move: $q_1 = 1$



Arc consistency: 4-queens

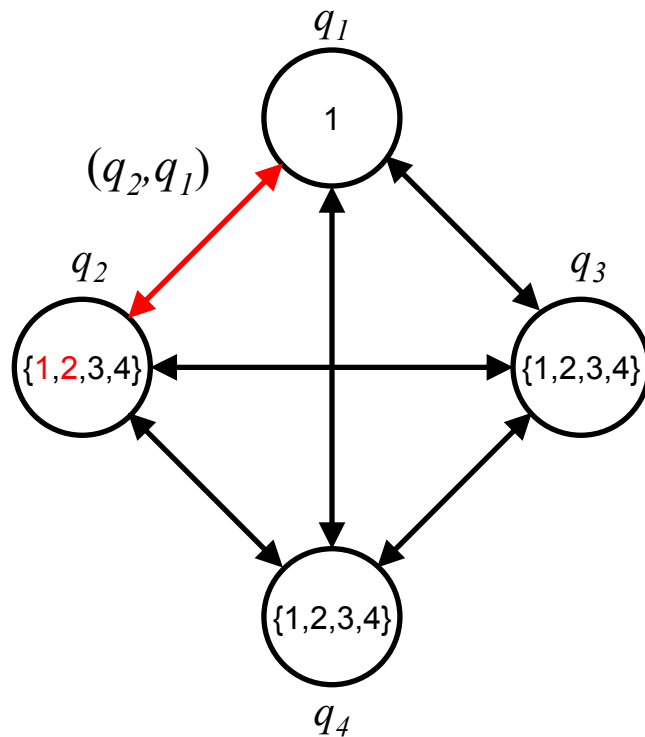


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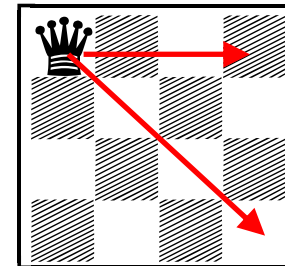


The arc (i,j) is *consistent* if each value at the tail j of the arc has at least one value at the head i that does not violate the constraints.

Arc consistency: 4-queens

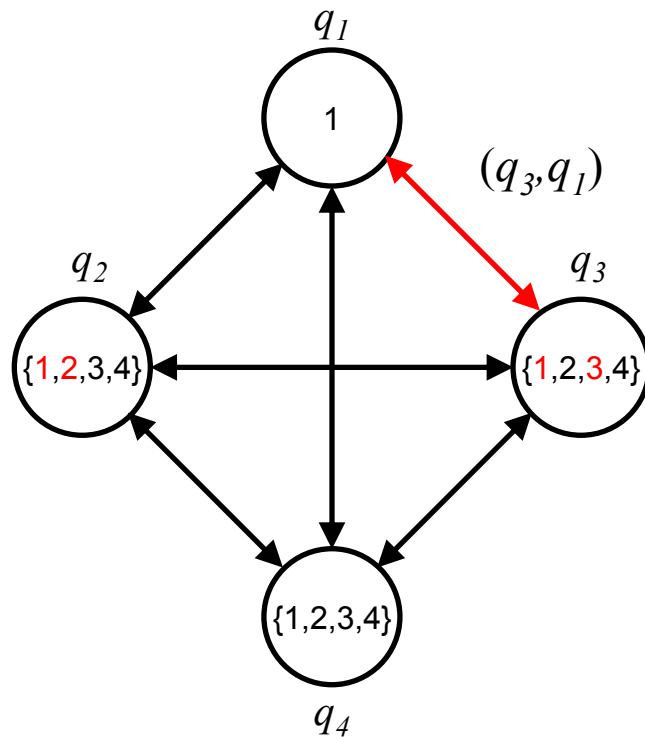


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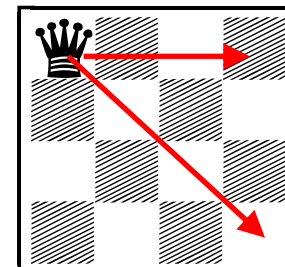


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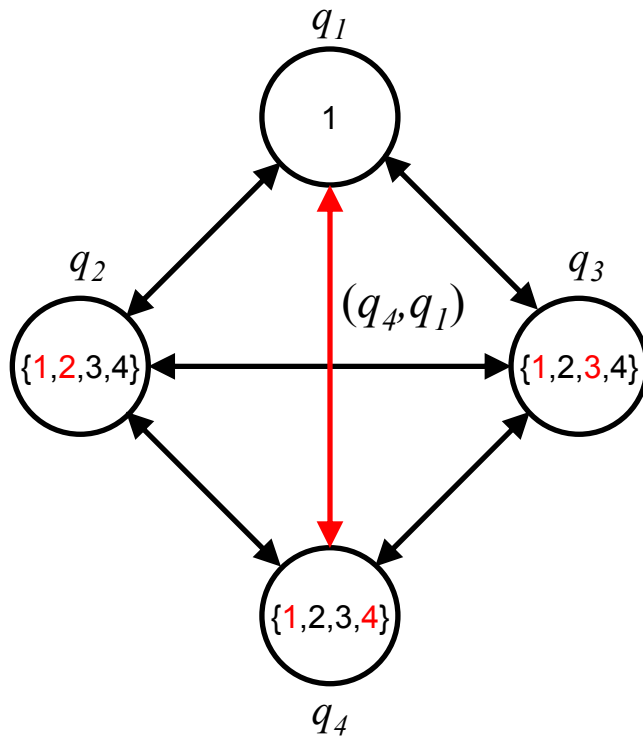


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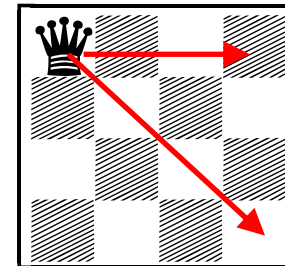


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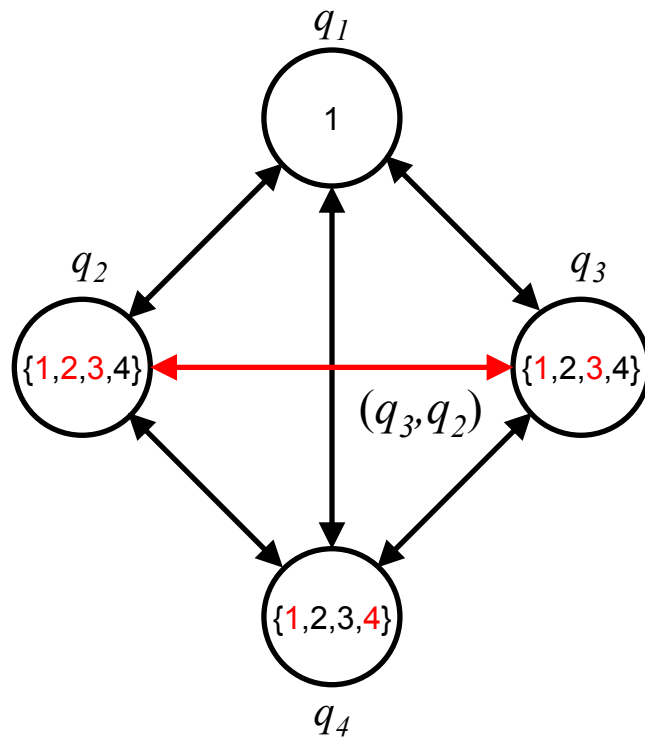


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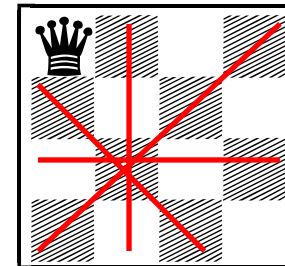


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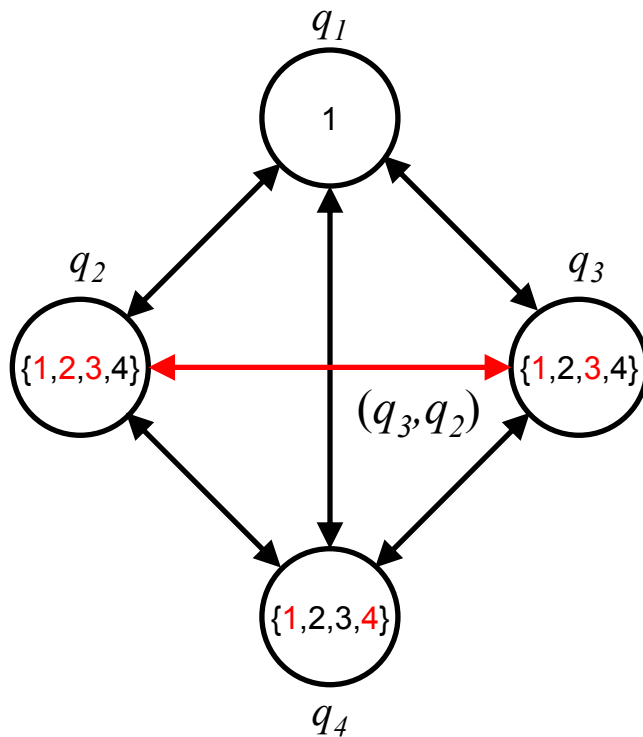


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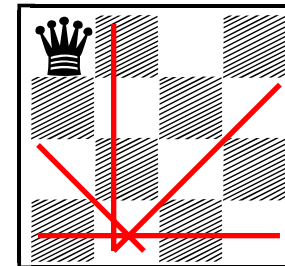


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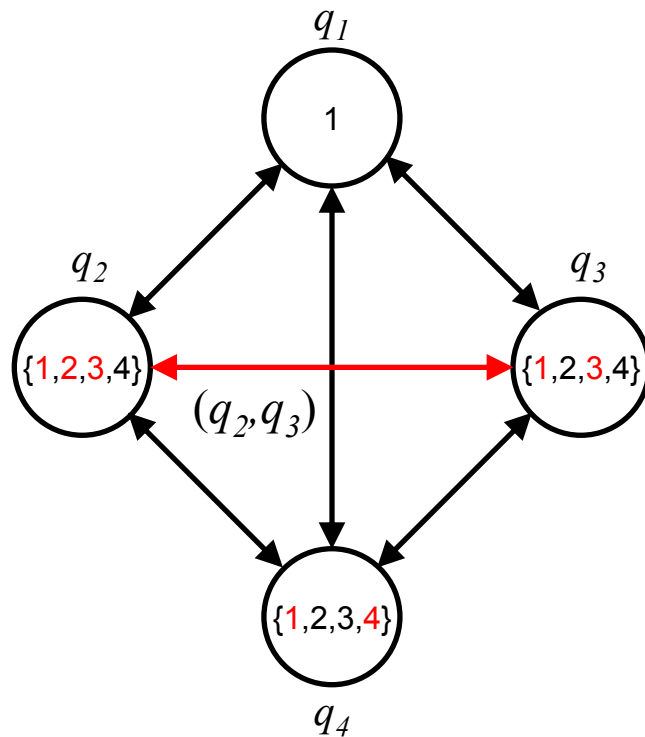


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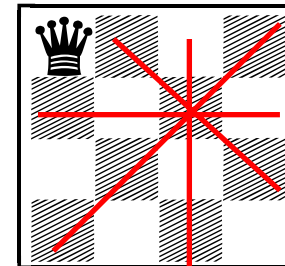


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Arc consistency: 4-queens

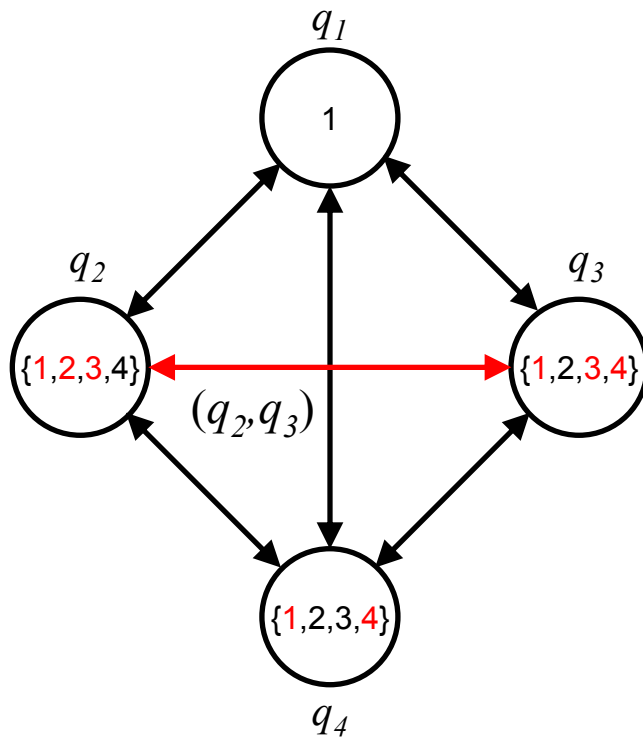


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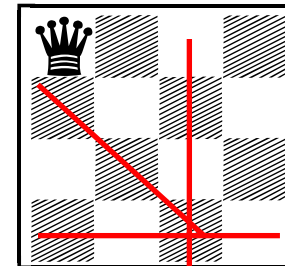


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Arc consistency: 4-queens

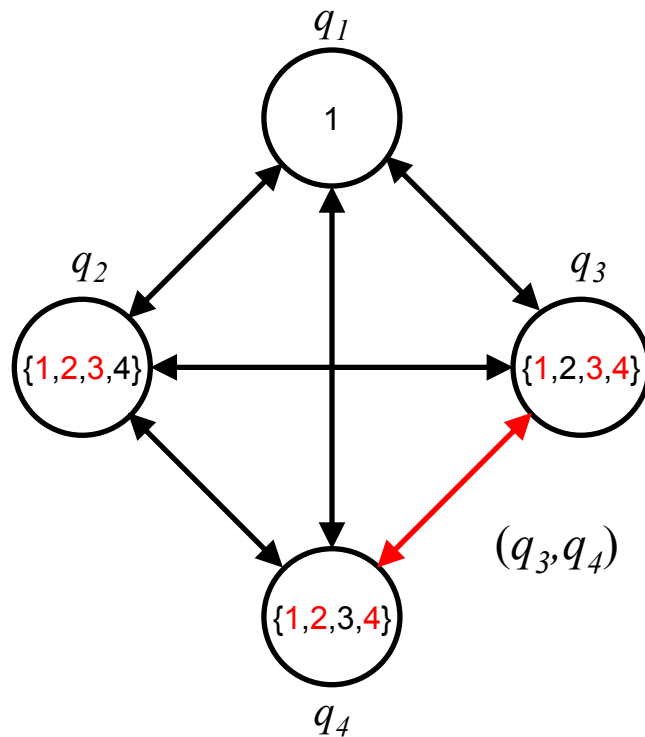


- q_i = queen placed in column i
- $\{1,2,3,4\}$ = The allowed values (row number) for the queen.
- First move: $q_1 = 1$

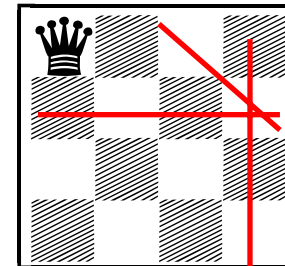


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Arc consistency: 4-queens

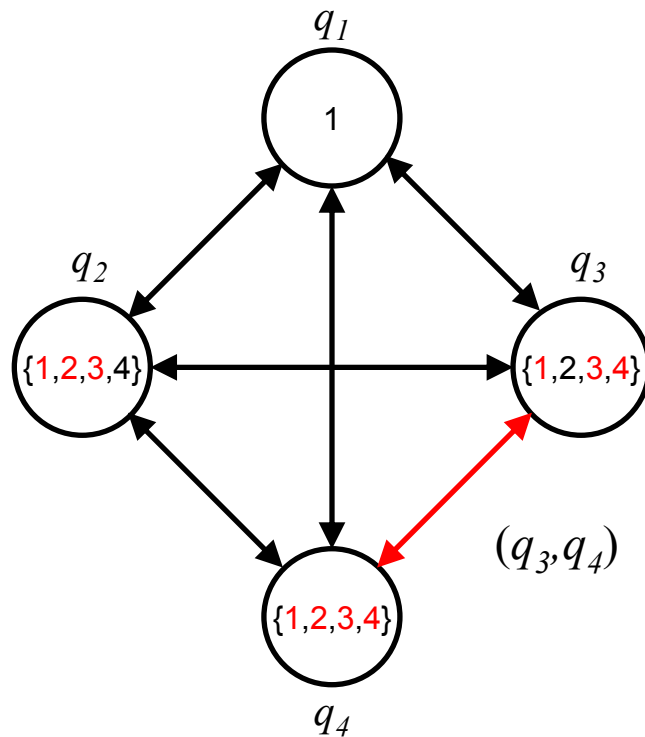


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- $\{1,2,3,4\}$ = The allowed values (row number) for the queen.
- First move: $q_1 = 1$

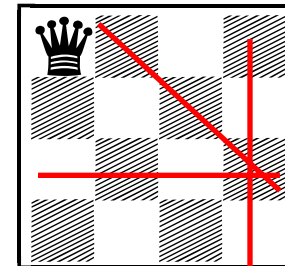


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Arc consistency: 4-queens



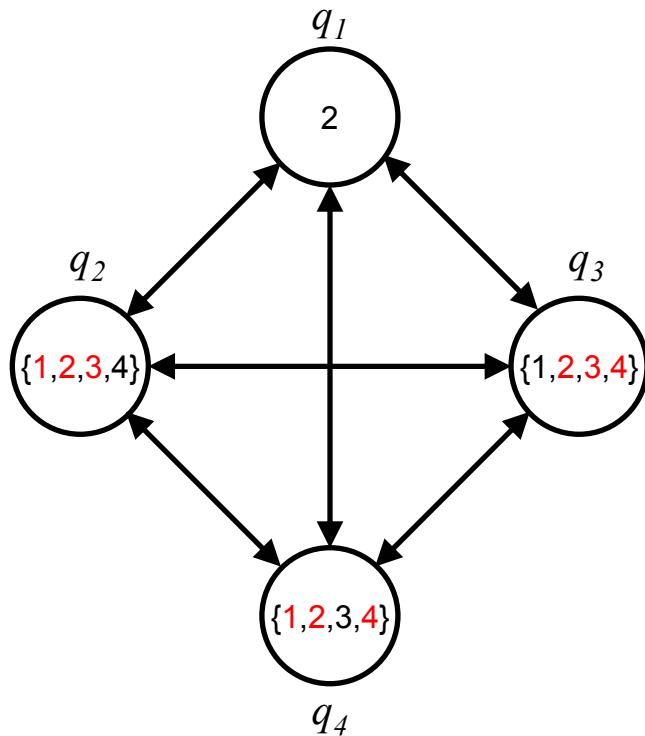
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- First move: $q_1 = 1$



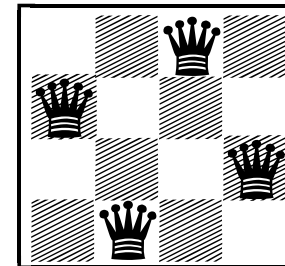
⇒ No solution with $q_1 = 1$

The arc (i,j) is *consistent* if each value at the tail j of the arc has at least one value at the head i that does not violate the constraints.

Arc consistency: 4-queens



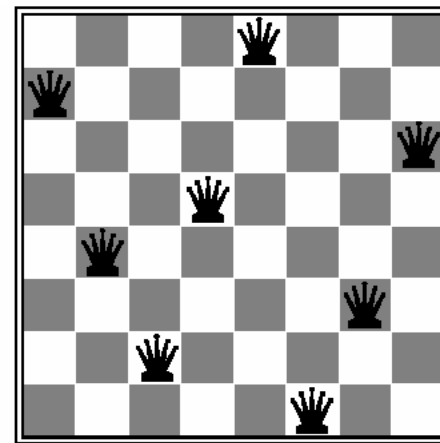
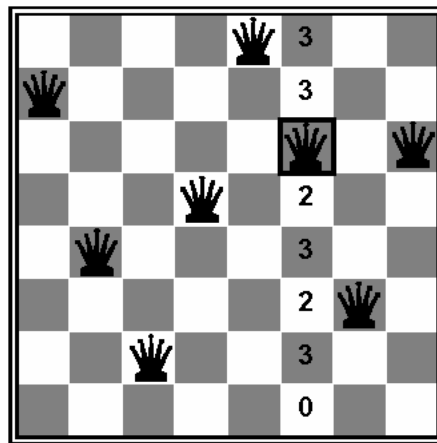
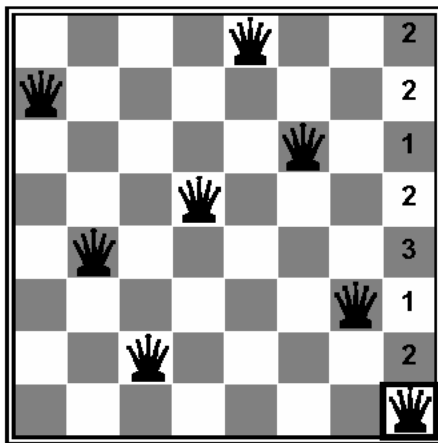
- q_i = queen placed in column i
- $\{1,2,3,4\}$ = The allowed values (row number) for the queen.
- First move: $q_1 = 2$



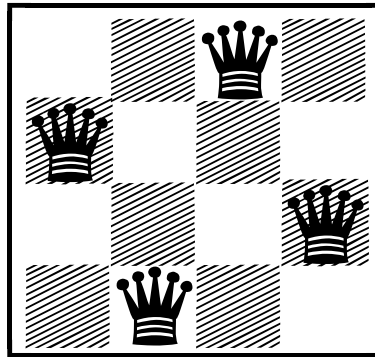
Arc consistency (constraint propagation) finds the solution

Local search: Simple and efficient

- Start with initial (invalid) state
- Modify this state, using the min-conflicts heuristic: Select the value that minimizes the number of conflicts
- Continue until a solution is found



Local search: 4-queens

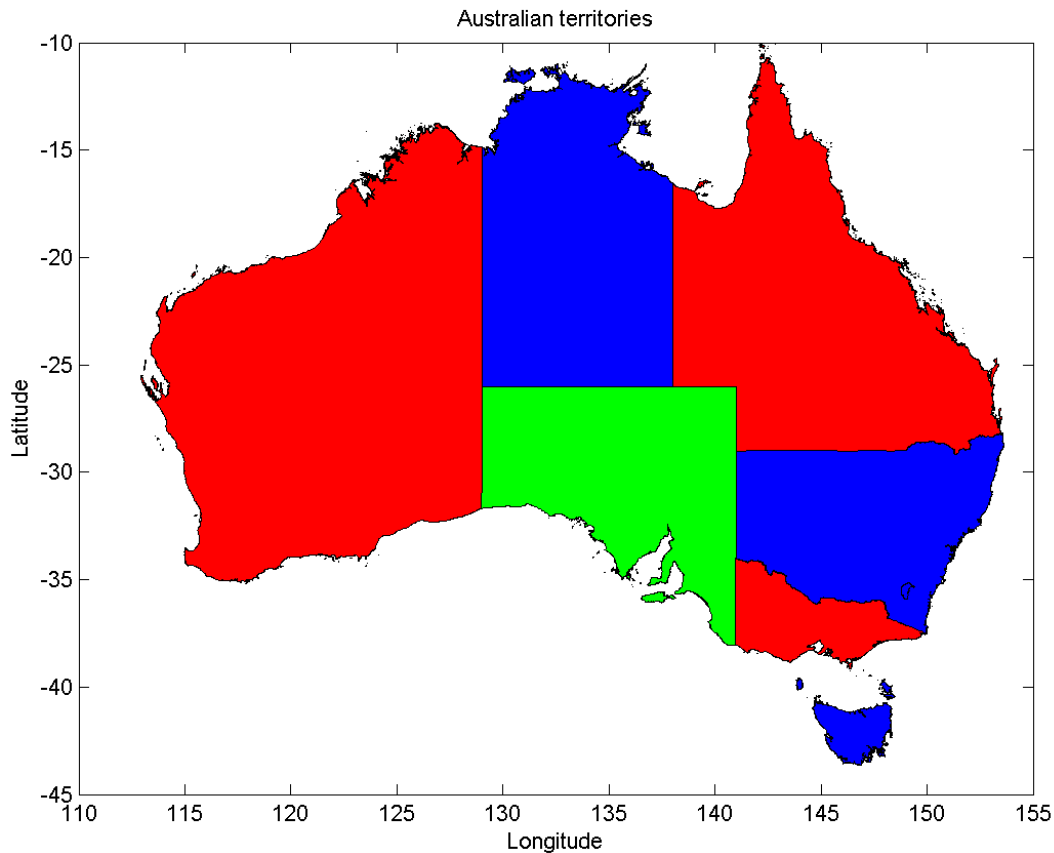


Stuck!

Choose random move
that does not increase
conflicts.

Solution in three moves!

Map coloring: Australia

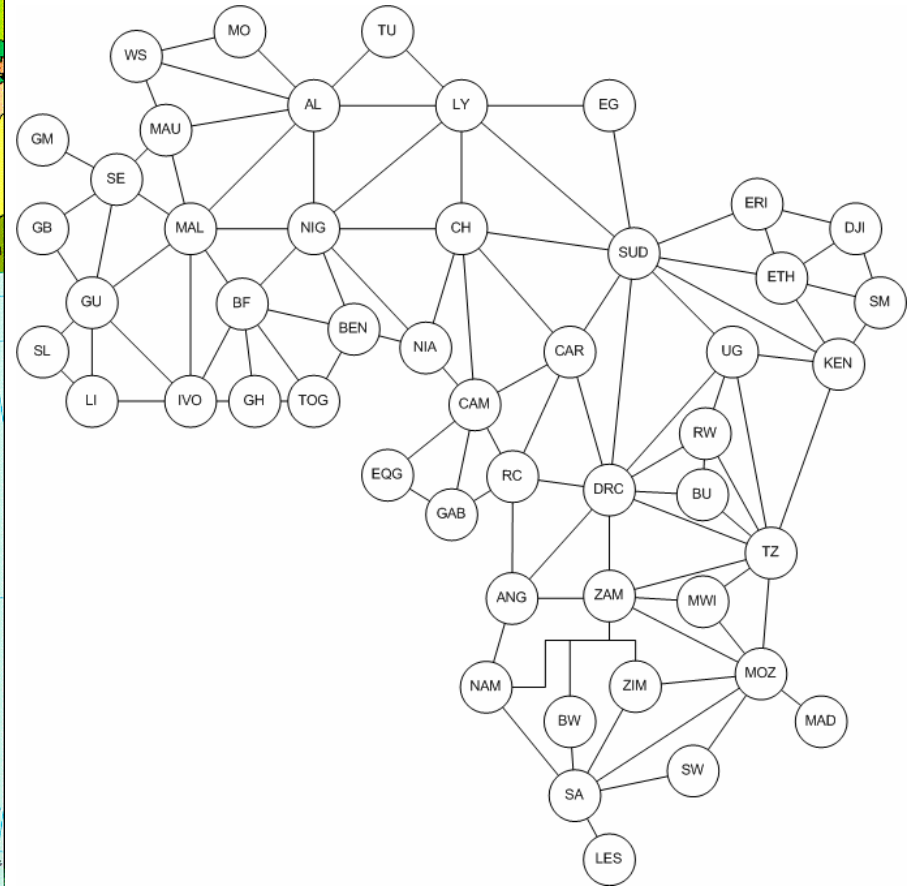


Using Java code @ AIMA site,
calling from within MATLAB.

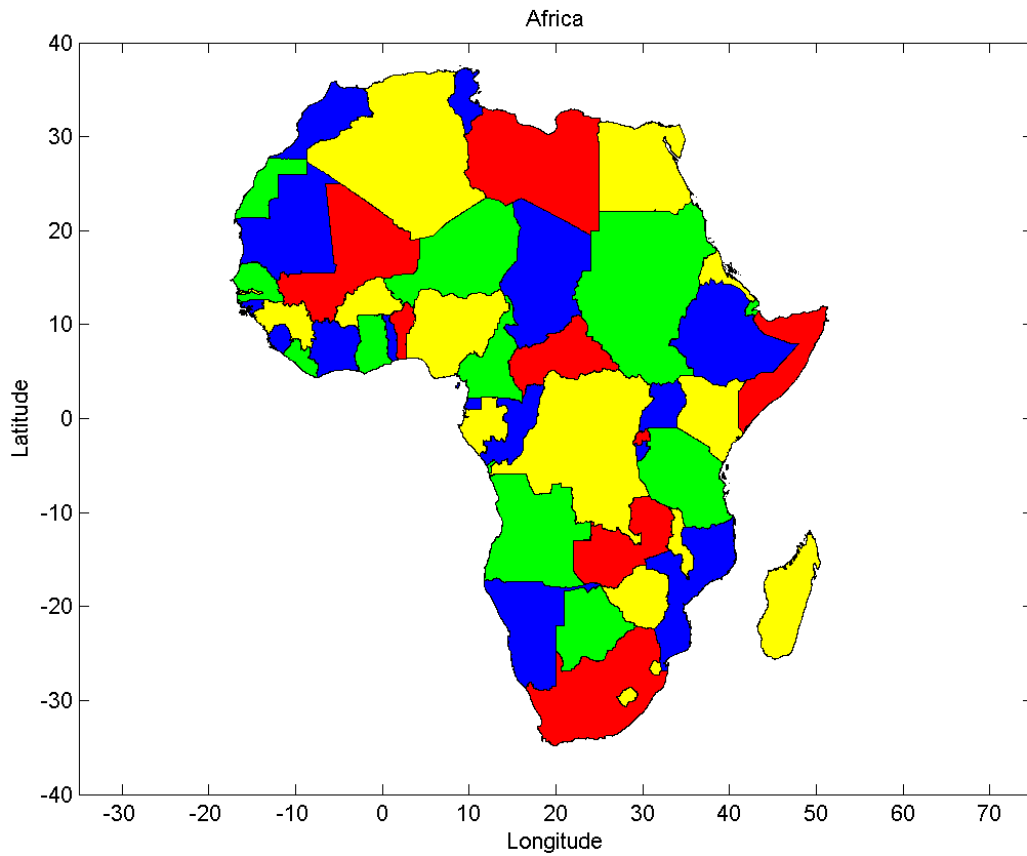
- Backtracking ~ 1.5 sec

7 variables (countries)
9 constraints
3 values (R,G,B)

Map coloring: Africa



Map coloring: Africa



Modified the AIMA Java code,
calling from within MATLAB.

- Backtracking \sim 5.5 min